Sanjay Pokkali

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EDUCATION

• University of Illinois - Urbana-Champaign

Master of Computer Science; GPA: 3.8/4.0

Urbana-Champaign, USA

Aug 2024 - Present

Coursework: Robot Manipulation, Principles of Safe Autonomy, Autonomous Vehicle System Eng., Computer Vision

• SSN College of Engineering, Anna University

Chennai, India

Bachelor of Engineering in Computer Science and Engineering; GPA: 8.10/10.0

Aug. 2017 - July 2021

EXPERIENCE

• Slip Robotics

Atlanta, USA

Robotics Intern May 2025 – Aug 2025

- * Developed a Gazebo Ignition Simulator for the SlipBot and UR20 arm for manipulation tasks.
- * Explored using MoveIt2 and ROS2 for controlling the UR20 arm.
- * Developed action recording capabilities for the SlipBot controller.

• RoboPIL Lab

Urbana-Champaign, USA

Jan 2025 - Present

Graduate Student Researcher

- * Investigating imitation learning approaches using Diffusion Policies to improve cloth folding with robots, while developing a realistic simulator to predict trends and assess policy performance.
- * Exploring methods to import and simulate soft body objects in MuJoCo for realistic cloth rendering.
- * Configured the Aloha Robot and developed scripts for camera calibration, policy training, and evaluation.
- * Formulated evaluation tests and built teleoperation and data collection scripts to convert demonstrations into datasets for benchmarking multiple approaches.

• Cleo Communications

Bengaluru, India

Software Engineer 1 - API Team

June 2023 - June 2024

- Enhancing Partner Screen [NodeJS, Angular, AWS: Lambda, RDS]:
 - * Enhanced the current Partner UI to provide enhanced functionality and improved the performance of the backend API by approximately 150%.
- API Whitelisting [NodeJS, Angular, AWS: Lambda]:
 - * Introduced the ability to whitelist certain IPs for API-based endpoints.
 - * Led the development of the user interface in Angular and the backend infrastructure in NodeJS.

Associate Software Engineer - API Team

Aug 2021 – June 2023

- Kong Infrastructure Upgrade [Ansible, Kong, AWS: AMI, EC2, RDS, Route53]:
 - * Performed a major upgrade of Kong Gateway with 0 downtime by using Ansible to interface with AWS and modify components.

Projects

- GEM Smart Summon and Obstacle Avoidance [Python, ROS]: Developed an end-to-end pipeline to equip the GEM e2 vehicle with autonomous lane following and navigation capabilities to reach a user's GNSS location.
- Semantic Visual SLAM [Python]: Built a Visual SLAM system that merges map data with labeled objects, providing autonomous vehicles with semantic maps for advanced navigation and scene understanding.

Programming Skills

- Languages: Python, C, C++, SQL, Java, JavaScript, TypeScript, HTML, CSS, Ansible
- Frameworks and Technologies: PyTorch, ROS, ROS2, Numpy, Pandas, NodeJS, Kubernetes, Git, AWS

ACHIEVEMENTS

• Winner, Most Innovative Solana Application Award, HackIllinois: Mar 2025